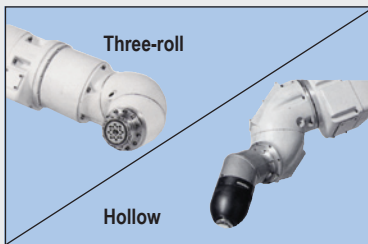
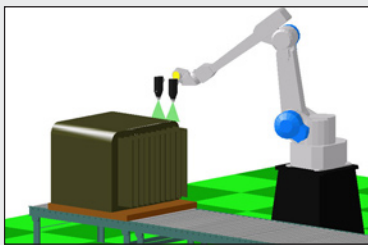




PAINTING OF INDUSTRIAL COMPONENTS



WRIST OPTIONS



MOTOSIM® EG OFF-LINE PROGRAMMING

## FEATURES & OPTIONS

- 2,829 mm reach with 3-roll wrist
- 2,834 mm reach with hollow wrist
- $\pm 0.5$  mm ( $\pm 0.02$ " ) repeatability
- Floor mount
- 3-roll or hollow style wrist available
- FM rating: Class 1, Div. 1 (explosion-proof)
- MotoSim® EG simulation software (optional)
- MotoMax® III warranty (standard)



*Motoman's PX2850 robot provides superior performance on large products*

• COATING • DISPENSING •

# PX2850

**Three-roll or hollow wrist**

### Versatile Paint Robot

The high-speed PX2850 robot is available with either a three-roll or hollow style wrist, providing versatility and superior performance in standard industrial and automotive painting applications.

The three-roll wrist design is ideal for painting contoured parts such as car bodies and interior/exterior surfaces. The hollow wrist is well-suited for painting horizontal and vertical planes.

The PX2850 robot is Factory Mutual (FM) approved for Class 1, Div. 1 use in hazardous environments. Both the three-roll and hollow wrist configurations feature a 10 kg (22.1 lb) payload capacity and a  $\pm 0.5$  mm ( $\pm 0.02$ " ) repeatability. The three-roll wrist has a 2,829 mm (111.4") reach while the hollow wrist has a 2,834 mm (111.6") reach. The PX2850 is available in a floor mounted configuration.

Optional devices such as 24-color change valve (CCV), flushable gear pump (FGP), flushing unit valve and master valve can be mounted on the upper arm resulting in reduced cycle time and wasted paint.

### Advanced XRC 2001-FM Controller

The advanced XRC 2001-FM controller features fast processing, easy-to-use INFORM II programming, and includes application-specific software for coating.

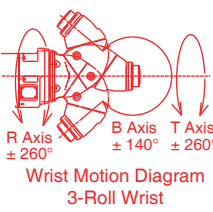
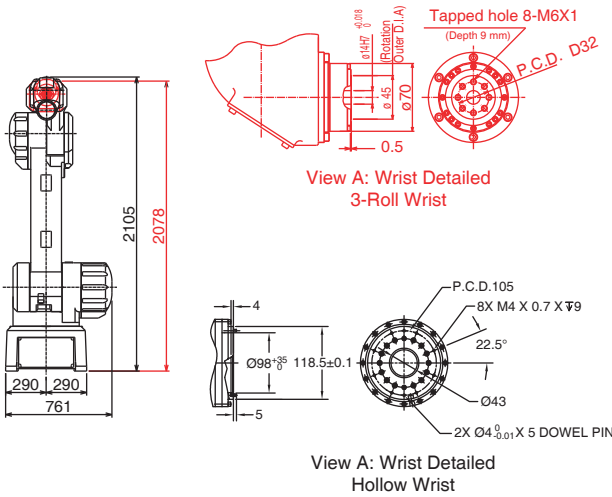
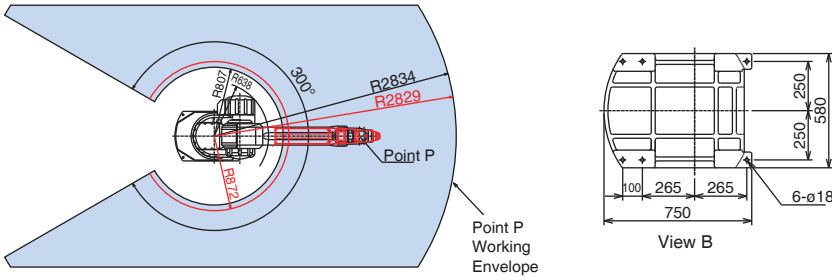
Two types of programming pendants are available – the standard model for use in non-explosive painting applications and as an option, an intrinsically-safe version for use in hazardous conditions.

The XRC 2001-FM coordinates operation of robot and painting devices, including the gun. It supports gun control instructions such as spray start/stop and painting conditions. All painting position parameters can be filed and saved.

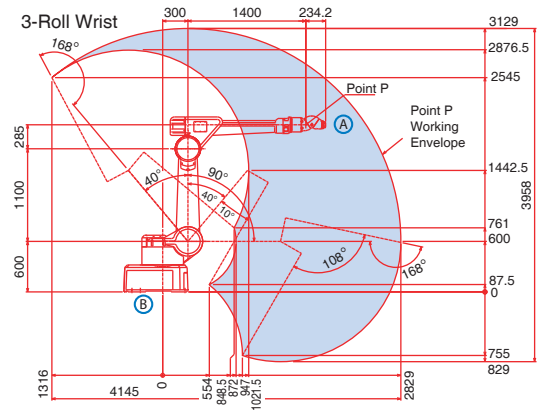
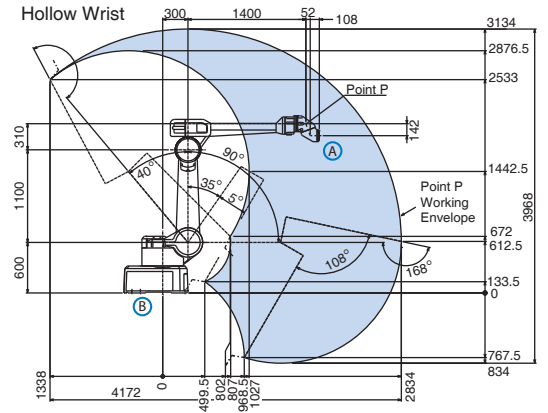
The XRC 2001-FM supports standard networks (such as DeviceNet, ControlNet, Profibus-DP, and Interbus-S), enabling connection to paint machine controllers and line controllers.

# PX2850 Robot

All dimensions are metric (mm) and for reference only. Please request detail drawings for all design/engineering requirements.



■ 3-roll wrist  
■ Hollow wrist



PX2850 SPECIFICATIONS		
Structure		Vertical jointed-arm type
Controlled Axes		6
Payload		10 kg (22.1 lbs.)
Vertical Reach		3-Roll: 3,958 mm (155.8") Hollow: 3,968 mm (156.2")
Horizontal Reach		3-Roll: 2,829 mm (111.4") Hollow: 2,834 mm (111.6")
Repeatability		±0.5 mm (0.02")
Maximum Motion Range	S-Axis (Turning/Sweep)	±150°
	L-Axis (Lower Arm)	+90°/-40°
	U-Axis (Upper Arm) <i>(relative angle of lower arm)</i>	3-Roll: +10°/-168° Hollow: +5°/-168°
	R-Axis (Wrist Roll)	3-Roll: ±260° Hollow: ±360°
	B-Axis (Bend/Pitch/Yaw)	3-Roll: ±140° Hollow: ±360°
	T-Axis (Wrist Twist)	3-Roll: ±260° Hollow: ±360°
Maximum Speed		2.0m/s
Approximate Mass		570 kg (1,256.9 lbs)
Brakes		All axes
Power Consumption		5 kVA
Allowable Moment	R-Axis	3-Roll: 34.1 N · m Hollow: 30.4 N · m
	B-Axis	3-Roll: 34.1 N · m Hollow: 19.6 N · m
	T-Axis	9.8 N · m
Allowable Moment of Inertia	R-Axis	3-Roll: 1.21 kg · m <sup>2</sup> Hollow: 0.97 kg · m <sup>2</sup>
	B-Axis	3-Roll: 1.21 kg · m <sup>2</sup> Hollow: 0.40 kg · m <sup>2</sup>
	T-Axis	0.10 kg · m <sup>2</sup>
Mounting		Floor

\*Specifications are for both 3-roll wrist and hollow wrist unless otherwise noted

XRC 2001-FM CONTROLLER SPECIFICATIONS	
Structure	Free-standing, enclosed type
Dimensions (mm)	800 (w) x 1,300 (h) x 600 (d) (31.5" x 51.2" x 23.6") (Scavenging unit (175 mm width) and protruding portion not included)
Approximate Mass	100 kg (220.5 lbs)
Cooling System	Indirect cooling
Ambient Temperature	During operation: 0° C (32° F) to 45° C (113° F) During transmit and storage: -10° C (14° F) to +60° C (140° F) 0° C (32° F) to 40° C (113° F) for programing pendant
Relative Humidity	90% max. non-condensing (85% or less for pendant)
Primary Power Requirements	3-phase, 200/220 VAC (+10% to -15%) at 50/60 Hz
Grounding	Grounding resistance: ≤100 ohms Separate ground required ≤10 ohms for intrinsically-safe pendant
Digital I/O	Specialized signals (hardware): 11 inputs/2 outputs General signals (standard max): 40 inputs/40 outputs Expandable to 256 inputs/256 outputs
Position Feedback	By absolute encoder
Drive Units	Servo packs for AC servomotors
Accel/Decel	Software servo control
Program Memory	5,000 steps and 3,000 instructions
Pendant Dim. (mm)	200 (w) x 325 (h) x 77 (d) (7.9" x 12.8" x 3.0")
Pendant Buttons Provided	Teach Play, Remote, Servo On, Start, Hold, Emergency Stop, Edit Lock
Safety	Emergency Stop Pushbuttons, 3-position Deadman, Brake Release Switches Meets ANSI/RIA R15.06-1999 standard Factory Mutual approved, Class 1, Div. 1
Scavenging Control	Equipped with scavenging control unit for internal pressure explosion-proof manipulators